

Automated inspection of microlens arrays

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Optical and Digital Image Processing - 07.04.2008



Outline

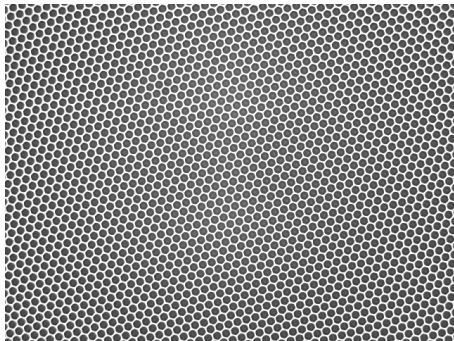
- 1 Microlens arrays inspection
- 2 Inspection methods and comparison
 - Reference subtraction
 - Blob analysis
- 3 Defect detection based on blob analysis
- 4 Semi-automated inspection system
- 5 Conclusion

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Microlens arrays

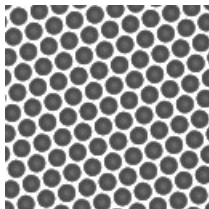
- Optical devices combining many small lenses.
- Used for collimation, illumination, imaging[?] ...



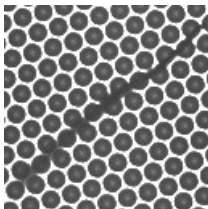
Specificities for this work:

- Small lenses :
 $10 \leq d \leq 50 \mu m$.
- Gaps coated with metal.
- Device with more than 2000000 lenses!

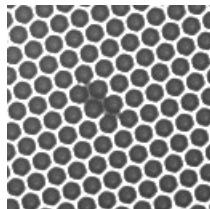
Inspection - Array defects



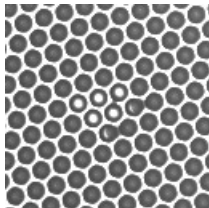
No defect



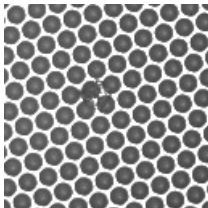
Filament on array



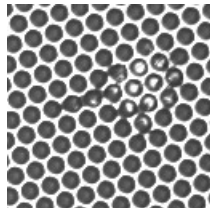
Missing metal



Metal covering

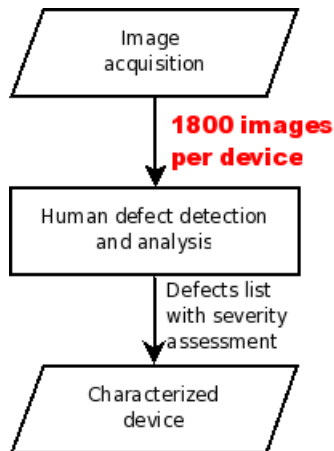


Bad lens



Defects combination

Semi-automated inspection system

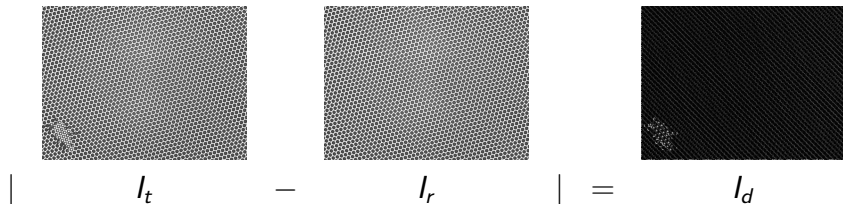


- The number of images to inspect is large.
- Human inspection is slow and reliability is low.
- Most images contain no defects.
- Automated defect detection can speed-up the inspection.

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Reference subtraction



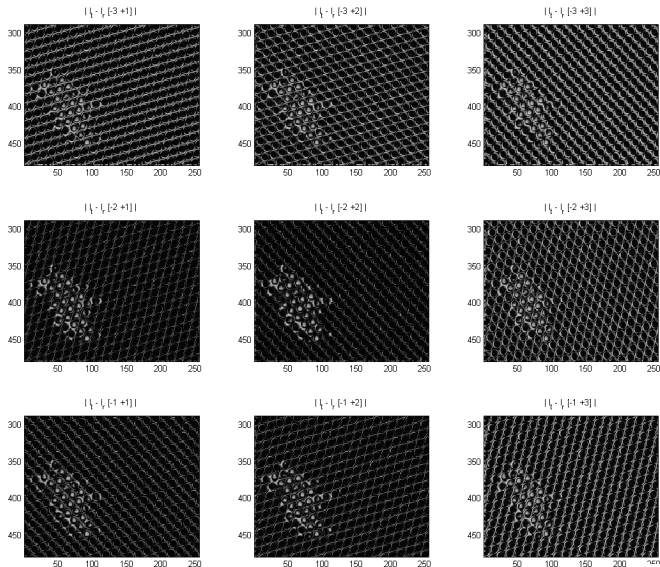
Advantages :

- Short processing time.
- Low memory requirements.

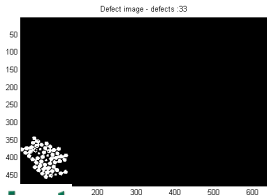
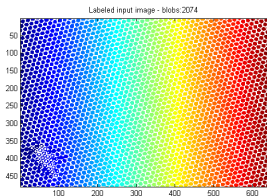
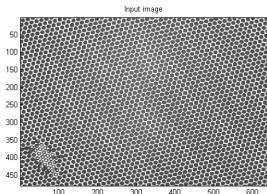
Disadvantages :

- Requires accurate alignment.
- Sensitive to **coarse sampling**.

Alignment and coarse sampling issue



Blob analysis



Advantages :

- Insensitive to alignment and coarse sampling.
- Simple, parametric lens models can be used.
- Easily adapted to new lens array geometry.

Disadvantage :

- Segmentation is critical.

Methods comparison

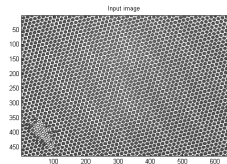
Challenge	Reference sub.	Blob analysis
Illumination may vary (gradients + vignetting)	—	0
No alignment between array lattice and image axes	— —	++
Defects may vary greatly in size and intensity characteristics	++	++
Short processing time (< 1 s)	++	+

Outline

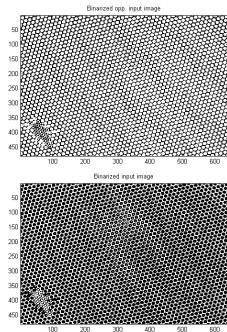
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Blob analysis - Process

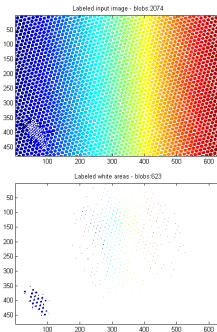
Input



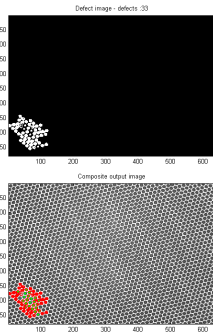
Segmentation



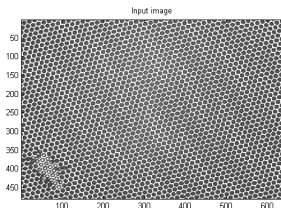
Morphology Labeling



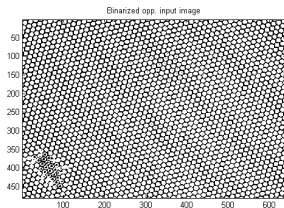
Defect detection



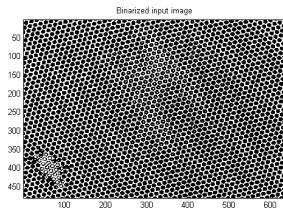
Segmentation



Global threshold θ



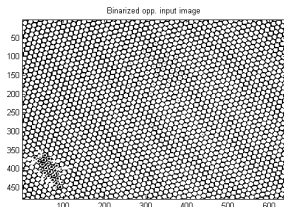
Lens regions



Metal + lens top regions

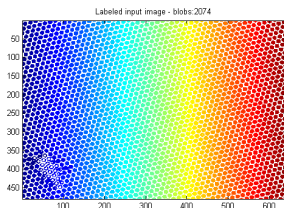
Morphology and labeling

Lens regions



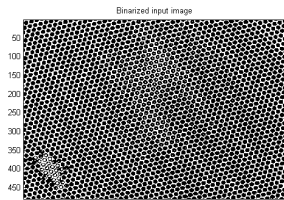
Denoising: Opening with 3x3 kernel

Labeling: V8 connected regions



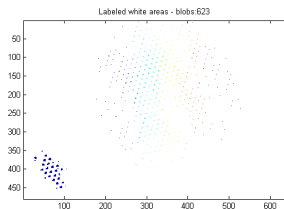
Lens blobs

Metal + lens top regions



Labeling: V8 connected regions

Removal of largest region (metal)

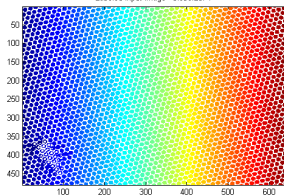


Lens top blobs

Blob area analysis

Lens blobs

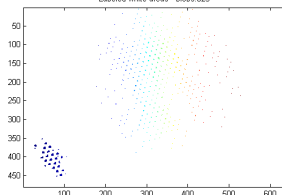
Labeled input image - blobs:2074



Area check: $A_{min,l} \leq A_l \leq A_{max,l}$

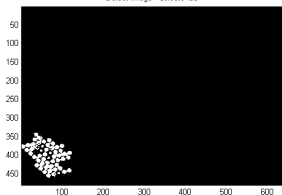
Lens top blobs

Labeled white areas - blobs:623



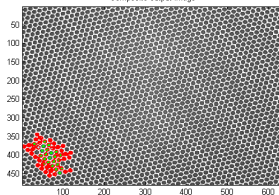
Area check: $A_m \leq A_{max,m}$

Defect image - defects:33



Defects map

Composite output image

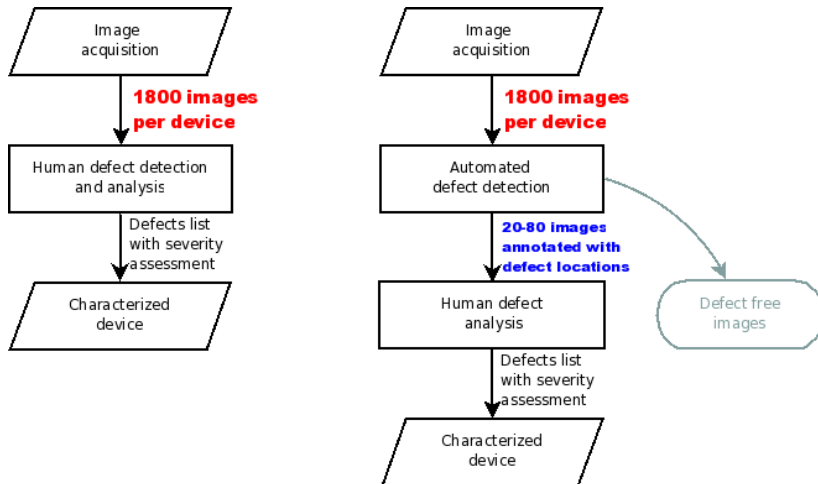


Composite output

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Semi-automated inspection system

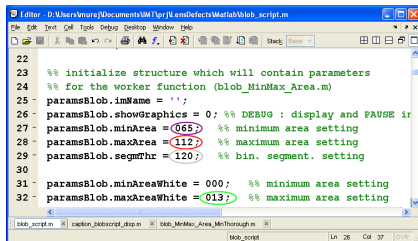


Blob area - Implementation

The defect detection module is implemented in Matlab and uses the Image Processing Toolbox.

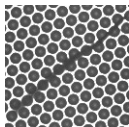
Parameters considered:

- segmentation intensity → `segmThr`
- lens area → `minArea`, `maxArea`
- maximum *hole* area → `maxWhiteArea`

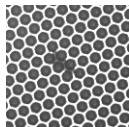


```
22
23 %% initialize structure which will contain parameters
24 %% for the worker function (blob_MinMax_Area.m)
25 paramsBlob.imName = '';
26 paramsBlob.showGraphics = 0; %% DEBUG : display and FAUSE ir
27 paramsBlob.minArea = 065; %% minimum area setting
28 paramsBlob.maxArea = 112; %% maximum area setting
29 paramsBlob.segmThr = 120; %% bin. segment. setting
30
31 paramsBlob.minAreaWhite = 000; %% minimum area setting
32 paramsBlob.maxAreaWhite = 013; %% maximum area setting
```

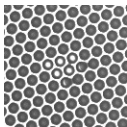
Blob area - Defect detection



maxLensArea



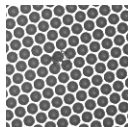
maxLensArea



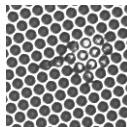
maxLensArea

minLensArea

maxMetalArea



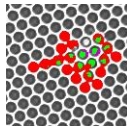
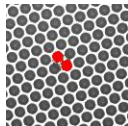
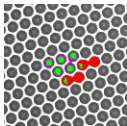
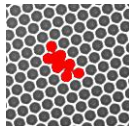
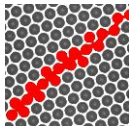
maxLensArea



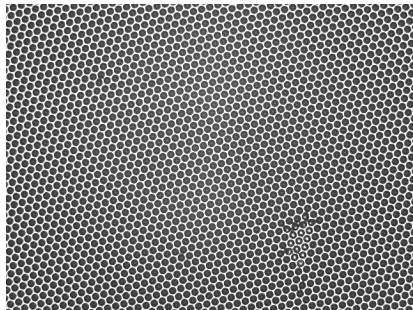
maxLensArea

minLensArea

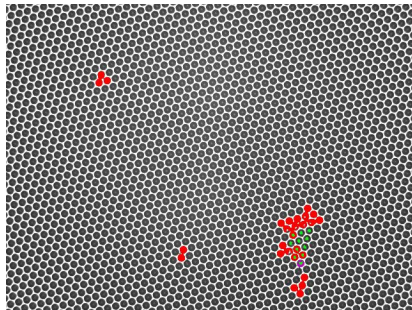
maxMetalArea



Blob area - Results

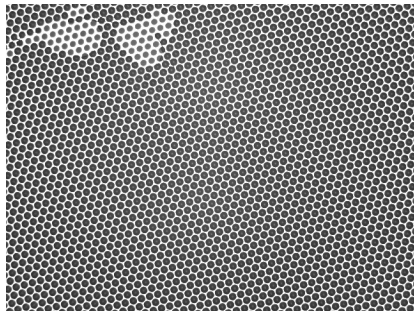


Test image

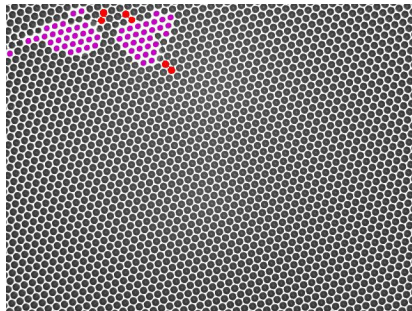


Composite output

Blob area - Results

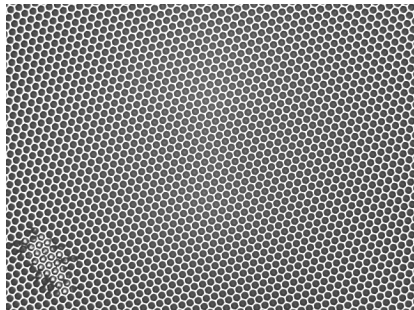


Test image

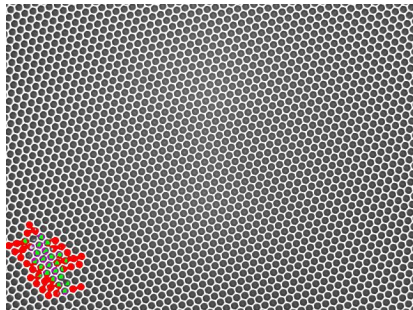


Composite output

Blob area - Results

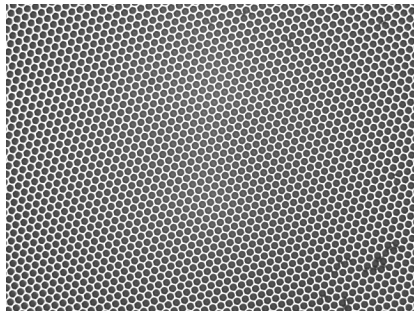


Test image

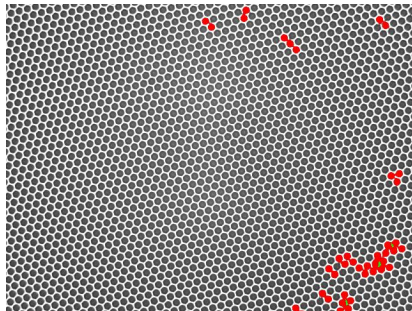


Composite output

Blob area - Results



Test image



Composite output

Blob area - Performance

Tests carried out on devices with a high number of defects.

Device	A	B
Images acquired	1804	1804
Defect detected automatically	446	242
Independent human annotation		
Defects found	133	58
False positive rate	17.4%	10.2%
False negative rate	0%	0%
Semi-automated human annotation		
Defects found	433	242
False positive rate	0.72%	0%
False negative rate	0%	0%

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Conclusions

- Image processing methods enabling automation of microlens arrays inspection were studied
- An automated **defect detection** system was realized, based on a blob analysis method
- Tests confirm that no defect goes through the system.
- Tests show a low false positive rate: the human supervisor is freed from the burden of watching large series of defect free images.
- Possible improvements:
 - Automatic parameter generation from reference images
 - Smarter segmentation methods (gradient based)

Acknowledgments

The authors would like to thank B. Putz and K. Weible at SUSS MicroOptics, for providing the annotated test image databases.

Thank you for your attention !



P. Nussbaomy, R. Voelkel, H.-P. Herzig, M. Eisner, and S. Haselbeck.

Design, fabrication and testing of microlens arrays for sensors and microsystems.

Pure Appl. Opt., 6:617–636, 1997.